

# Introduction to Bayesian Methods

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# Overview

- 1 Introduction
  - Let's meet & Credits
- 2 Bayesian Methods
  - General Concepts
  - Bayes Rule
  - Model Estimation
- 3 Discussion
  - Why Bayes?
  - BMA and DMA
  - Final Example
- 4 Literature

# Let's meet

- Julia Soloveva
- Senior undergraduate student at MSU
- Fields of interest: Insurance Markets, Public Economics, Econometrics
- All questions are welcome throughout the lecture

# Credits

Today's lecture is based on materials of the "Introductory Bayesian Time Series Methods" course at Barcelona Graduate School of Economics



**Professor Gary Koop**  
University of Strathclyde

- Bayesian Basics
- Bayesian Methods for Fat Data
- Bayesian State Space Models

All relevant literature is listed later

# Bayesian Philosophy - Blessed Uncertainty

## Bayesian

- ① Unknown things (parameters, models, forecasts) are random variables
- ② We want distributions and means of unknown parameters
- ③ Few rules of probability

*Nothing is true, everything is permitted (c)*

## Frequentist

- ① "True" values exist
- ② We want point estimates and confidence intervals
- ③ Need to make assumptions (e.g. no unit roots)

# Bayesian Probability Rule

## Definition (Conditional Probability)

The conditional probability of A given B, denoted as  $Pr(A|B)$ , is the probability of event A occurring given event B has occurred.

Conditional probability summarizes what is known about B given A  
Well-known formulae:

$$Pr(A|B) = \frac{Pr(A,B)}{Pr(B)}$$

$$Pr(B|A) = \frac{Pr(A,B)}{Pr(A)}$$

Combined together will produce Bayes Theorem

# Bayes Theorem

## Theorem (Bayes Theorem)

$$Pr(A|B) = \frac{Pr(B|A)Pr(A)}{Pr(B)}$$

Above is expressed in terms of two events, A and B. However, can be interpreted as holding true for random variables, A and B with probability density functions replacing Pr()s in previous formulae.

# Econometrician's view

## What does a humble researcher want?

- Estimate parameters in a model (regression coefficients)
- Compare different models (hypothesis testing)
- Predict (make forecasts)

## What do we have being Bayes disciples?

- Let  $y$  be data,  $y^*$  be unobserved data (e.g. a forecast),  $M_i$  for  $i = 1, \dots, m$  be a set of models, each of which depends on some parameters  $\Theta^i$ .
- Model comparison based on posterior model probability:  $p(M_i|y)$ . Which model is the most likely?
- Prediction based on the predictive density  $p(y|y^*)$ .



## Parameter Estimation in a Given Model

- Assume a single model which depends on parameters  $\Theta$   $M(\Theta)$ . We want to find properties (mean? distribution?) of the posterior  $p(\Theta|y)$ .

- Let us rewrite the Bayes rule:

$$p(B|A) = \frac{p(A|B)p(B)}{p(A)}$$

Replace B by  $\Theta$  and A by  $y$  to obtain:

$$p(\Theta|y) = \frac{p(y|\Theta)p(\Theta)}{p(y)}$$

*Note:* for estimation we can ignore  $p(y)$  since it does not depend on  $\Theta$

- $p(\Theta|y)$  - the posterior. Given the data, what do we know about  $\Theta$ ?
- $p(y|\Theta)$  - likelihood function. How well do our parameters predict the data?
- $p(\Theta)$  - prior density. What do we know about parameters without seeing the data?

# Prior Talk

## Sounds unscientific?

- More information is good - if we do have prior information, we should include it.
- "Empirical Bayes" methods to estimate prior from the data
- Training sample prior - divide our sample into training sample and regression sample
- Prior sensitivity analysis

# Prediction

Prediction is based on predictive density  $p(y^*|y)$ .

- Marginal density can be obtained from a joint density through integration:

$$p(y^*|y) = \int p(y^*, \Theta|y) d\Theta$$

- Term inside integral can be rewritten as:

$$p(y^*|y) = \int p(y^*|y, \Theta)p(\Theta|y) d\Theta$$

- Prediction involves the posterior and  $p(y^*|y), \Theta$

# Model Comparison (Hypothesis Testing)

- Models denoted by  $M_i$  for  $i = 1, \dots, m$ .  $M_i$  depends on parameters  $\Theta^i$ .
- $p(M_i|y)$  is *posterior model probability*
- Using Bayes rule with  $B = M_i$  and  $A = y$  we obtain:  
$$p(M_i|y) = \frac{p(y|M_i)p(M_i)}{p(y)}$$
- $p(M_i)$  - prior model probability
- $p(y|M_i)$  - marginal likelihood

# Marginal Likelihood Calculation

Posterior can be written as:  $p(\Theta^i|y, M_i) = \frac{p(y|\Theta^i, M_i)p(\Theta^i|M_i)}{p(y|M_i)}$

Integrate both sides with respect to  $\Theta^i$ , use fact that

$\int p(\Theta^i|y, M_i)d\Theta^i = 1$  and rearrange:  $p(y|M_i) = \int p(y|\Theta^i)p(\Theta^i|M_i)d\Theta^i$

Marginal likelihood depends only on the prior and the likelihood.

# Model Comparison

For comparison of two models we calculate *Posterior odds ratio*

Definition (Posterior Odds Ratio)

$$PO_{ij} = \frac{p(M_i|y)}{p(M_j|y)} = \frac{p(y|M_i)p(M_i)}{p(y|M_j)p(M_j)}$$

## Two Models Case

$$p(M_1|y) + p(M_2|y) = 1$$

$$PO_{12} = \frac{p(M_1|y)}{p(M_2|y)}$$

and we get:  $p(M_1|y) = \frac{PO_{12}}{1+PO_{12}}$

$$p(M_2|y) = 1 - p(M_1|y)$$

### Definition (The Bayes Factor)

$$BF_{ij} = \frac{p(y|M_i)}{p(y|M_j)}$$

# Why Bayes?

"Big" Data may be "tall" or "fat"

- Tall Data = data with many observations
- Fat Data = data with many variables

Fat Data is becoming common in macroeconomics.

Why include all the variables?

- The more data the better
- Want to avoid the omitted variable bias - misspecification
- Although the multicollinearity problem remains. How do we deal with it?



# Bayes and Fat Data

Why not use conventional methods? Intuition:

- Number of observations,  $N$ , reflects amount of information in the data
- Number of variables,  $K$  reflects dimension of things trying to estimate with that data
- If  $N$  is small relative to  $K$  we're trying to do too much with too little information

What happens to least squares?

- Standard errors are growing, troubles with confidence intervals
- Fat data may be "noisy" - good in-sample fit, bad out-of-sample forecasting

## Too Many Variables

Why don't we do hypothesis testing to reduce  $K$ ? Because we get a *multiple testing problem*.

- With  $K=41$  there are 41 different restricted regressions which drop one of the explanatory variables.
- There are  $\frac{K(K-1)}{K}$  restricted regressions which drop two variables.
- etc.
- In total we have  $2^K = 2\,199\,023\,255\,552$  possible regression models.

How do we choose? Obviously, no t-tests.

# Bayesian Model Averaging - the Concept

We don't need no model selection. Away with single model and estimates based on it.

Model averaging - take a weighted average of estimates or forecasts from all models with weights given by  $p(M_r|y)$ .

- Let  $M_r$  for  $r = 1, \dots, R$  denote  $R$  models
- If  $\phi$  is a parameter to be estimated (or a function of parameters) or a variable to be forecast, then the rules of probability imply:

$$p(\phi|y) = \sum^R p(\phi|y, M_r)p(M_r|y)$$

- Allows for formal treatment of model uncertainty. Allows for uncertainty which model generated the data.

# Dynamic Model Averaging

Another problem on the way: many time series variables.

Consider the problem: regression of inflation on many predictors. What may be the pitfalls?

- Regressions with many predictors can over-fit
- Marginal effects of predictors change over time (parameter change/structural breaks)
- The model itself may change
- Sometimes the random walk may be better!

Bayesians have an answer to that - Dynamic Model Averaging

# The Final Example

- Consider a generalized Phillips curve: inflation depends on lagged inflation, unemployment and other predictors (change in consumption expenditures, change in real GDP, change in employment etc.).

One possible option - Time Varying Parameter Model (TVP)

$$y_t = z_t \Theta_t + \epsilon_t$$

$$\Theta_t = \Theta_{t-1} + \eta_t$$

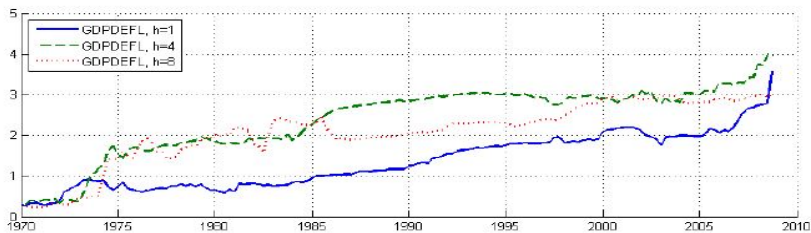
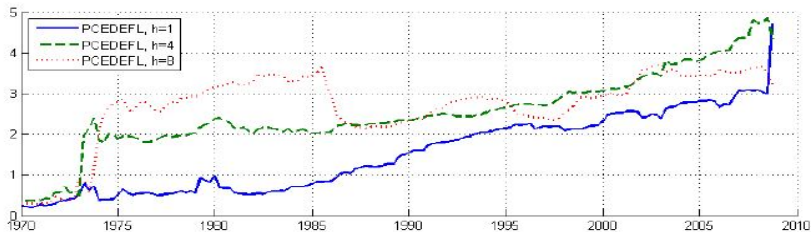
Where errors are i.i.d.

Disadvantage - same predictors are used at all points in time

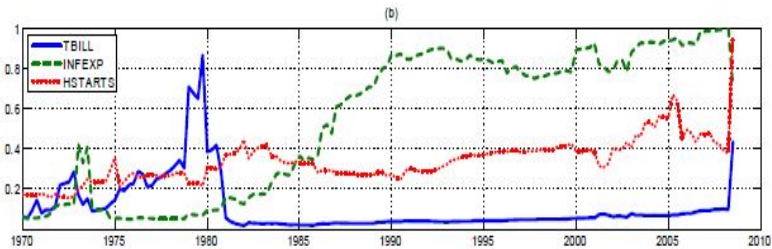
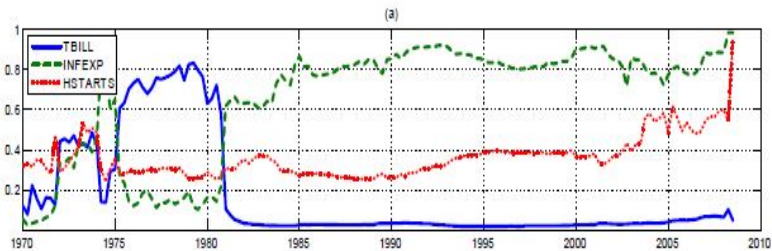
An example based on paper: Koop and Korobilis "Forecasting Inflation Using Dynamic Model Averaging" (2012, International Economic Review)

- Generalized Phillips Curve: inflation dependent on lagged inflation, unemployment and other predictors
- Other predictors: percentage changes in personal consumption, private residential fixed investment, real GDP; the log of housing starts, Treasury Bill market rate
- Two measures of inflation: core inflation, GDP deflator
- 3 forecasting horizons:  $h = 1, 4, 8$

# Dynamic Model Averaging - Results



Expected number of predictors



Posterior probability of inclusion of predictors



## Textbooks:

- Gary Koop, Bayesian Econometrics
- Walter Enders, Applied Econometric Time Series; Barber, Cemgil, Chiappa Bayesian Time Series - for overview of Bayes theory in time series
- Giordani, Pitt, Kohn Bayesian Inference for Time Series State Space Models - an article on State Space Methods

## Useful links:

- Course materials, tutorials and sample codes
- Bayesian Econometrics for Central Bankers

# Boo!

